

Multimodal optimization: a variational approach

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PROBLEM STATEMENT

Fitness function

- $\ell: \mathbb{R}^d \rightarrow \mathbb{R} \rightsquigarrow$ can be **non-convex** and **multimodal**.

Goals

- locate **multiple local and global maxima** in one run,
- identify the **"widest" maxima**.

Approach

Our optimization algorithm is inspired by the **Bayesian learning rule** [2], using:

- a **variational formulation** of the problem and a relevant **variational family**,
- a **procedure** based on **natural gradients**.

In addition, we use an **annealed objective function**.

ANNEALED VARIATIONAL OBJECTIVE

Variational formulation

$$q^* = \arg \max_{q \in \mathcal{P}(\mathbb{R}^d)} \mathbb{E}_q[\ell(\xi)].$$

The solutions are of the form $q^* = \sum_{i=1}^L c_i \delta_{\xi_i^*}$, where

- $(\xi_i^*)_{1 \leq i \leq L}$ are the global maxima of ℓ ,
- $(c_i)_{1 \leq i \leq L}$ are weights in $[0, 1]$ such that $\sum_{i=1}^L c_i = 1$.

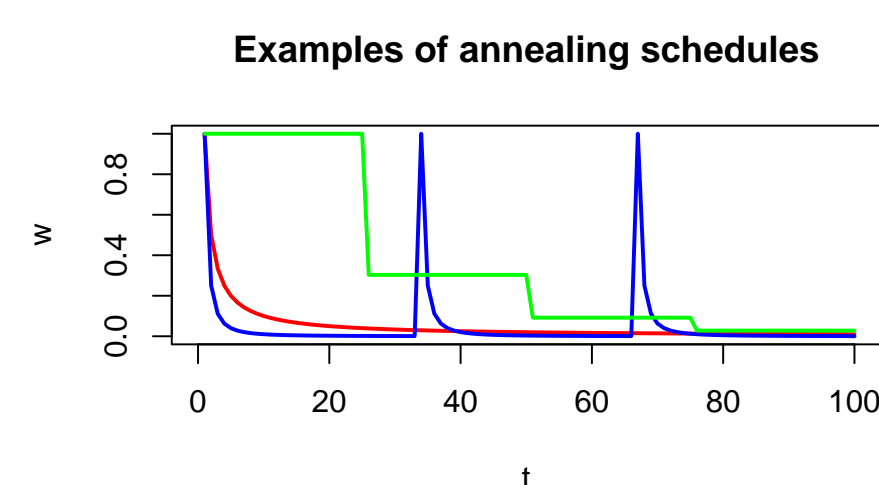
Entropy penalty

$$q^{*,\omega} = \arg \max_{q \in \mathcal{P}(\mathbb{R}^d)} \mathbb{E}_q[\underbrace{\ell(\xi)}_{f_\omega(\xi)} - \omega \log q(\xi)], \text{ where } \omega > 0.$$

Convergence result

$$q^{*,\omega} \xrightarrow{\omega \rightarrow 0} q^* = \sum_{i=1}^L c_i^* \delta_{\xi_i^*},$$

where for all $1 \leq i \leq L$, $c_i^* \propto \det(-\nabla^2 \ell(\xi_i^*))^{-1/2}$.



Annealing schedule

For optimization, set $(\omega_t)_{t \geq 1}$ with $\omega_t \xrightarrow{t \rightarrow 0} 0$.

VARIATIONAL FAMILY: GAUSSIAN MIXTURES

Search restriction to Gaussian mixtures with K components

$$q_\Lambda(\xi) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{m}_k, \mathbf{S}_k^{-1}).$$

Parameterization

$\Lambda = (\log(\pi_1/\pi_K), \dots, \log(\pi_{K-1}/\pi_K), \lambda_1, \dots, \lambda_K)$, where $\lambda_k = (\mathbf{S}_k \mathbf{m}_k, -\mathbf{S}_k/2)$.

Targeted result

- the means $(\mathbf{m}_k)_{1 \leq k \leq K}$ converge to different modes of ℓ ,
- the covariance matrices $(\mathbf{S}_k^{-1})_{1 \leq k \leq K}$ shrink to 0,
- the weights $(\pi_k)_{1 \leq k \leq K}$ give information on the curvature at the modes.

Effect of entropy penalty

$\omega > 0$ induces an (intra- and) inter-component repulsion term.

OPTIMIZATION: NATURAL GRADIENT ASCENT

Natural gradient ascent: update rule

$$\Lambda_{t+1} = \Lambda_t + \rho_t \mathbf{F}(\Lambda_t)^{-1} \nabla_{\Lambda} \underbrace{\mathbb{E}_{q_{\Lambda_t}}[f_{\omega_t}(\xi; \Lambda_t)]}_{\mathcal{L}_{\omega_t}(\Lambda_t)}.$$

- $\mathbf{F}(\Lambda_t)$ is the **Fisher information matrix**.
- The natural gradient gives the steepest direction in the Riemannian manifold (parameter space) [1].
- Convergence is quick, but computation of $\mathbf{F}(\Lambda_t)^{-1}$ is usually involving.

Case of Gaussian mixtures [4]

$$\mathbf{S}_{k,t+1} = \mathbf{S}_{k,t} - \frac{2\rho_t}{\pi_{k,t}} \nabla_{\mathbf{S}_k^{-1}} \mathcal{L}_{\omega_t}(\Lambda_t),$$

$$\mathbf{m}_{k,t+1} = \mathbf{m}_{k,t} + \frac{\rho_t}{\pi_{k,t}} \mathbf{S}_{k,t+1}^{-1} \nabla_{\mathbf{m}_k} \mathcal{L}_{\omega_t}(\Lambda_t),$$

$$\log(\pi_{k,t+1}/\pi_{K,t+1}) = \log(\pi_{k,t}/\pi_{K,t}) + \rho_t \nabla_{\pi_k} \mathcal{L}_{\omega_t}(\Lambda_t).$$

Weight gradient

$$\nabla_{\pi_k} \mathcal{L}_{\omega}(\Lambda) = \mathbb{E}_{\mathcal{N}(\mathbf{m}_k, \mathbf{S}_k^{-1})}[f_{\omega}(\xi; \Lambda)] - \mathbb{E}_{\mathcal{N}(\mathbf{m}_K, \mathbf{S}_K^{-1})}[f_{\omega}(\xi; \Lambda)].$$

Black-box method

$$\nabla_{\mathbf{m}_k} \mathcal{L}_{\omega}(\Lambda) = \pi_k \mathbb{E}_{\mathcal{N}(\mathbf{m}_k, \mathbf{S}_k^{-1})}[\mathbf{S}_k(\xi - \mathbf{m}_k) f_{\omega}(\xi; \Lambda)],$$

$$\nabla_{\mathbf{S}_k^{-1}} \mathcal{L}_{\omega}(\Lambda) = \frac{\pi_k}{2} \mathbb{E}_{\mathcal{N}(\mathbf{m}_k, \mathbf{S}_k^{-1})}[(\mathbf{S}_k(\xi - \mathbf{m}_k)(\xi - \mathbf{m}_k)^T \mathbf{S}_k - \mathbf{S}_k) f_{\omega}(\xi; \Lambda)].$$

Bonnet and Price's theorems

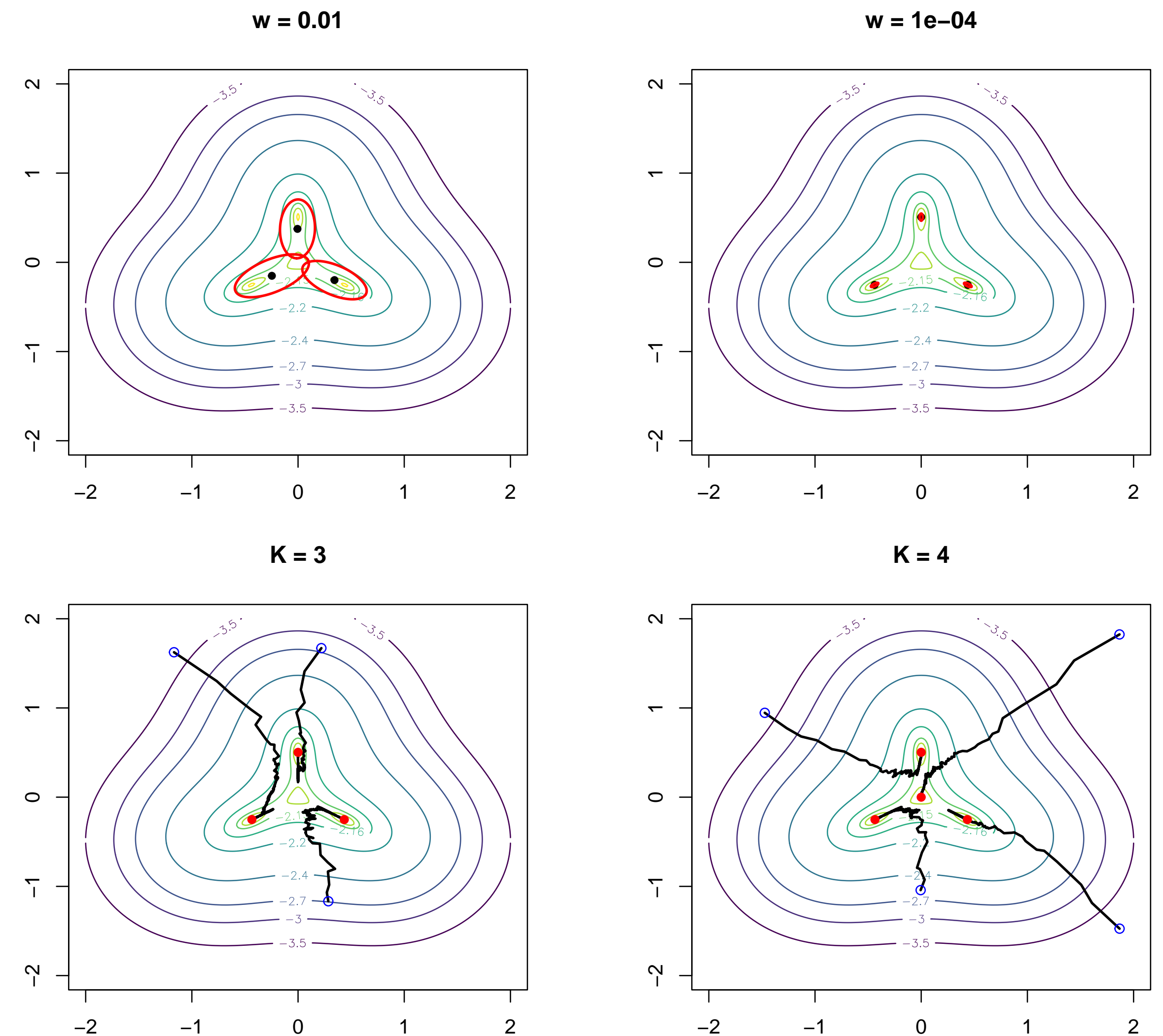
$$\nabla_{\mathbf{m}_k} \mathcal{L}_{\omega}(\Lambda) = \pi_k \mathbb{E}_{\mathcal{N}(\mathbf{m}_k, \mathbf{S}_k^{-1})}[\nabla_{\xi} f_{\omega}(\xi; \Lambda)],$$

$$\nabla_{\mathbf{S}_k^{-1}} \mathcal{L}_{\omega}(\Lambda) = \frac{\pi_k}{2} \mathbb{E}_{\mathcal{N}(\mathbf{m}_k, \mathbf{S}_k^{-1})}[\nabla_{\xi}^2 f_{\omega}(\xi; \Lambda)].$$

SIMULATIONS

Example 1: Gaussian mixture with 3 components, 3 global + 1 local modes

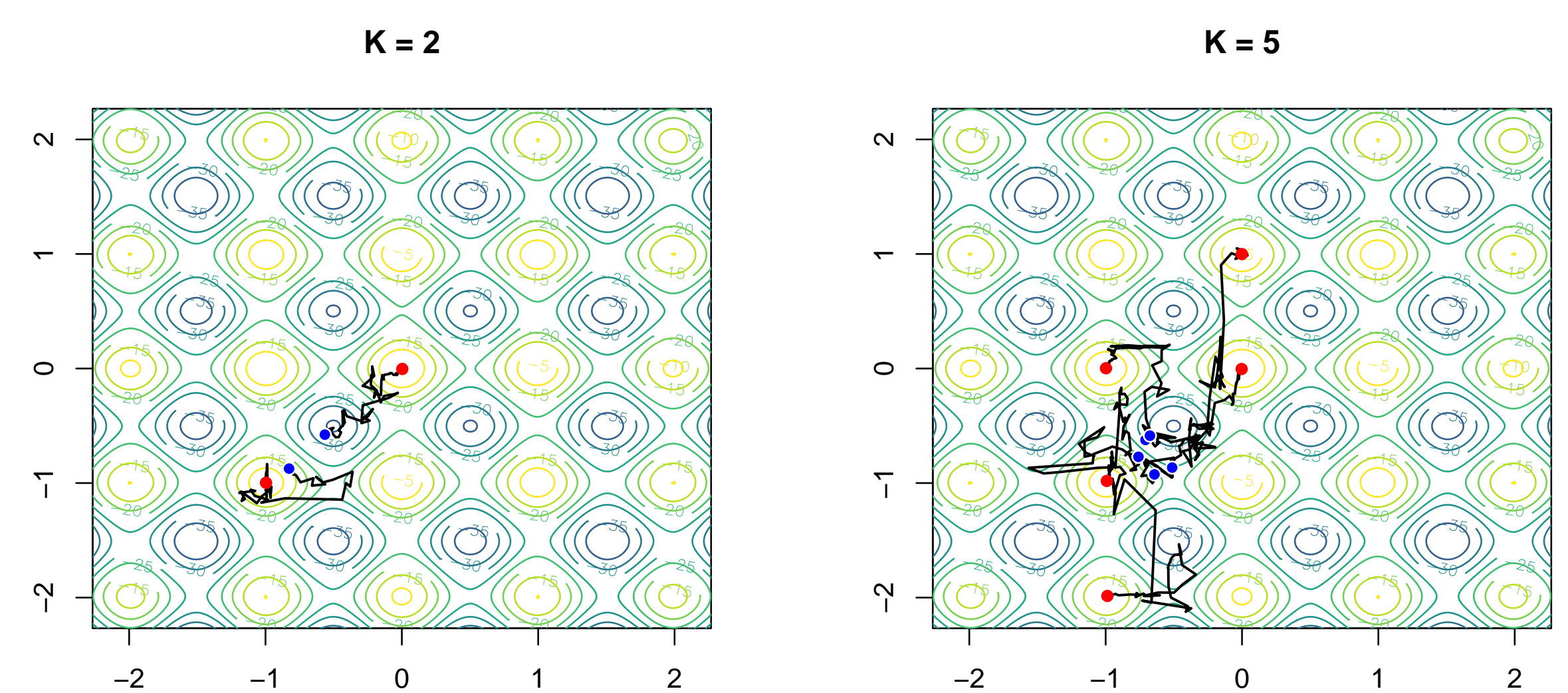
Effect of the entropy penalty: approached solutions $q_{\Lambda^{*,\omega}}$ for a fixed $\omega > 0$, $K = 3$



- The entropy term helps to **prevent the means from converging to similar modes**.

Example 2: Rastrigin function

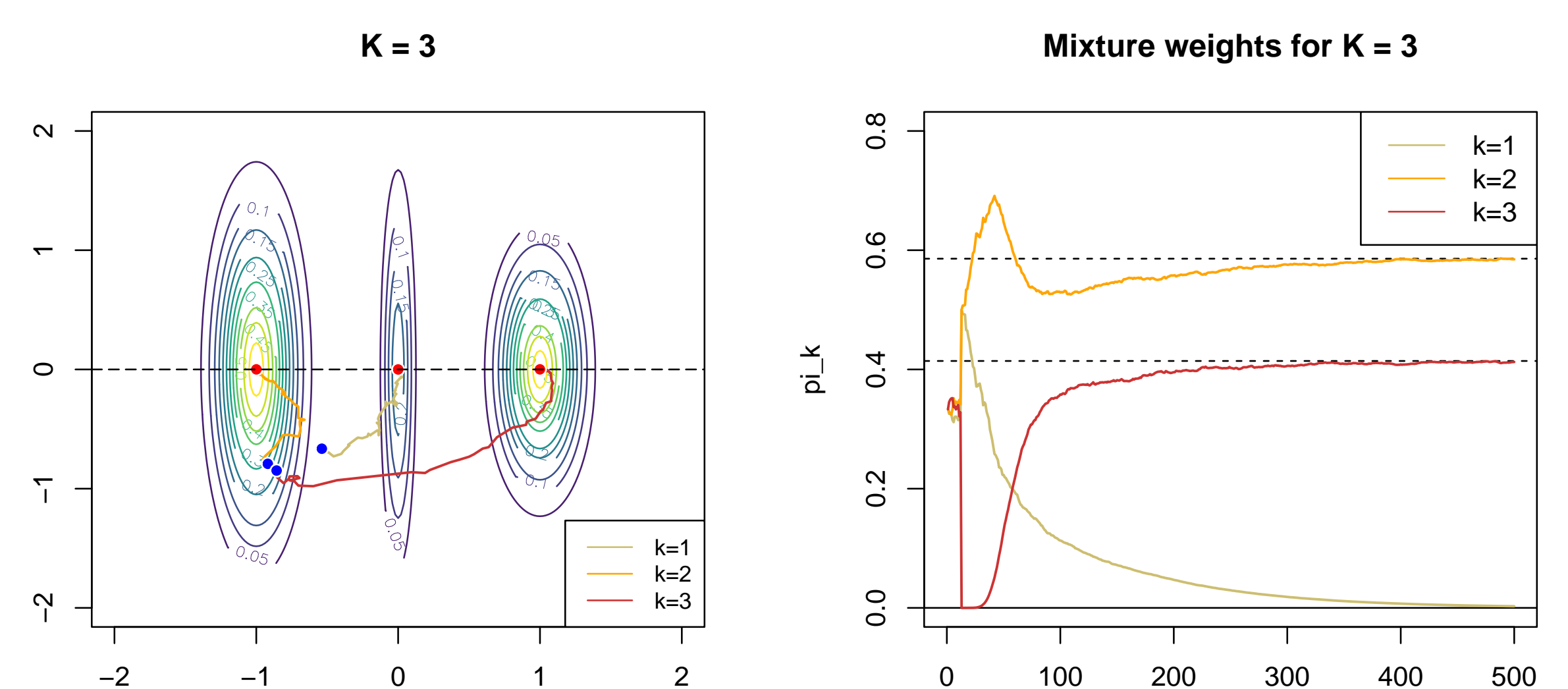
Paths of the means $(\mathbf{m}_k)_{1 \leq k \leq K}$ under annealing schedule $\omega_t = \omega_0/t^{1.5}$



- The optimization problem is non-convex, therefore **local modes can be found**.

Example 3: Gaussian mixture with 3 components, 2 global + 1 local modes

Paths of the means $(\mathbf{m}_k)_{1 \leq k \leq K}$ under annealing schedule $\omega_t = \omega_0/t$



- The **weights are proportional to the determinant of the Hessian matrix of ℓ at the "highest" modes found**.

FUTURE WORK

- Elements from **evolutionary algorithms** [5] can be incorporated to find the global maxima more easily.
 \rightsquigarrow However, this means local maxima are less likely to be detected.
- **Application** to posterior mode identification in **Bayesian inverse problems** [3].

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